Transferability-Guided Cross-Domain Cross-Task Transfer Learning 2022

Yang Tan, Yang Li*, Shao-Lun Huang, Xiao-Ping Zhang

Tsinghua-Berkeley Shenzhen Institute, Tsinghua University * Corresponding author

Abstract

To solve the "when and what to transfer" problem under the challenging cross-domain crosstask transfer learning setting, we propose a unified framework namely OTCE (Optimal Transport based Conditional Entropy), which can not only quantitatively evaluate that how much the source task (model) benefits the learning of the target task, but also serves as a loss function to optimize the source representations to become more transferable to the target task.



Figure 1: Illustration of different transfer learning settings.

When to Transfer (Transferability Estimation)^[1]

Transferability Definition



What to Transfer (Learn Transferable Representation) ^[2]

- **OTCE-based** Finetune
 - > Maximizing OTCE score will lead to a more transferable feature representation.

 $\hat{\theta}_s^* = \arg\min \ H_{\pi^*}(Y_t|Y_s)$ $= -\arg\min_{\hat{\theta}_s} \sum_{y_t \in \mathcal{Y}_t} \sum_{y_s \in \mathcal{Y}_s} \hat{P}(y_s, y_t) \log \frac{\hat{P}(y_s, y_t)}{\hat{P}(y_s)}$

 $\operatorname{Trf}(S \to T) = \begin{cases} \mathbb{E}\left[\log P(y_t | x_t; \theta_s, h_t)\right] & (\operatorname{Retrain head}) \\ \mathbb{E}\left[\log P(y_t | x_t; \theta_t, h_t)\right] & (\operatorname{Finetune}) \end{cases}$

> Our OTCE metric aims to efficiently approximate the empirical transferability.

OTCE Metric

- > Embed samples into feature space $z_s^i = \theta_s(x_s^i)$ $z_t^i = \theta_s(x_t^i)$
- > Solve the Optimal Transport problem to obtain an optimal coupling matrix π^* ,

$$OT(Z_s, Z_t) \triangleq \min_{\pi \in \mathcal{P}(Z_s, Z_t)} \sum_{i,j=1}^{m,n} c(z_s^i, z_t^j) \pi_{ij} - \lambda H(\pi)$$

where $c(\cdot, \cdot) = || \cdot - \cdot ||_2^2$ is the cost metric, and $H(\pi) = -\sum_{i=1}^m \sum_{j=1}^n \pi_{ij} \log \pi_{ij}$ is the entropic regularizer.

 \succ Compute $\hat{P}(y_s, y_t)$ and $\hat{P}(y_s)$ as:

$$\hat{P}(y_s, y_t) = \sum_{i, j: y_s^i = y_s, y_t^j = y_t} \pi_{ij}^*, \ \hat{P}(y_s) = \sum_{y_t \in \mathcal{Y}_t} \hat{P}(y_s, y_t)$$

> **OTCE** score is computed as the Negative Conditional Entropy

$$OTCE = -H_{\pi^*}(Y_t|Y_s)$$
$$= \sum_{y_t \in \mathcal{Y}_t} \sum_{y_s \in \mathcal{Y}_s} \hat{P}(y_s, y_t) \log \frac{\hat{P}(y_s, y_t)}{\hat{P}(y_s)}$$

 $\rightarrow -H(Y_t|Y_s)$ lower bounds the log likelihood of the target classifier using the source feature extractor.^[3]

Experiments

Input data







Algorithm 6.1 OTCE-based finetune **Require:** source dataset $D_s = \{(x_s^i, y_s^i)\}_{i=1}^m$ target dataset $D_t = \{(x_t^i, y_t^i)\}_{i=1}^n$ source feature extractor θ_s 1: Initialize $\hat{\theta}_s = \theta_s$ 2: while sampling mini-batches within one epoch do Generate mini-batch $B_s = \{(\theta_s(x_s^i), y_s^i)\}_i^M$ Generate mini-batch $B_t = \{(\hat{\theta}_s(x_t^i), y_t^i)\}_i^N$ Update $\hat{\theta}_{s}$ via maximizing F-OTCE(B_{s}, B_{t}) 6: end while 7: Initialize $\theta_t = \hat{\theta}_s$ 8: Randomly initialize h_t 9: while θ_{i} , h_{i} not converge do Update θ_t , h_t using equation (6.2) 11: end while

Note: F-OTCE and OTCE are substitutes for each other.

Experiments

Cross-domain few-shot transfer learning experiments.

Model	Method	$MNIST \rightarrow Omniglot$	$Caltech101 \rightarrow MiniImageNet$
FewshotNet	MAML [32] MatchingNet [30] ProtoNet [33] RelationNet [31] Vanilla finetune OTCE-based finetune	$\begin{array}{c} 88.60 \pm 1.14\% \\ 87.92 \pm 1.10\% \\ 83.11 \pm 1.34\% \\ 69.35 \pm 1.62\% \\ 91.30 \pm 0.95\% \\ \textbf{92.32} \pm \textbf{0.87\%} \end{array}$	$\begin{array}{c} 28.23 \pm 0.44\% \\ 44.75 \pm 1.30\% \\ 50.40 \pm 1.35\% \\ 29.55 \pm 0.61\% \\ 49.49 \pm 1.27\% \\ 51.36 \pm \mathbf{1.33\%} \end{array}$
LeNet	Vanilla finetune OTCE-based finetune	$\begin{array}{c} 86.11 \pm 1.10\% \\ 90.52 \pm 0.94\% \end{array}$	-
ResNet-18	Vanilla finetune OTCE-based finetune	-	$\begin{array}{c} 48.48 \pm 1.39\% \\ 50.02 \pm 1.34\% \end{array}$

> Visual comparison: the optimized models exhibit both higher transfer accuracy and OTCE scores.



Discussion

Conclusions

- > OTCE evaluates transferability for both image classification and semantic segmentation tasks.
- \succ It also helps the source model to be more transferable to the target task.
- It has been applied in source model (task) selection, multi-source feature fusion, etc.

Future works

- > Deeply understand the theoretical explanations of our method.
- \succ Explore more applications in transfer learning, e.g., domain generalization.

Reference

- [1] Y. Tan, Y. Li, SL. Huang. OTCE: A Transferability Metric for Cross-Domain Cross-Task Representations. In CVPR 2021.
- [2] Y. Tan, Y. Li, SL. Huang, XP. Zhang. Transferability-Guided Cross-Domain Cross-Task Transfer Learning. In arXiv:2207.05510.
- [3] A. Tran, C. Nguyen, T. Hassner. Transferability and Hardness of Supervised Classification Tasks. In ICCV 2019.





Shenzhen Research Institute of Big Data



香港中文大學(深圳) The Chinese University of Hong Kong, Shenzhen

 清华-伯克利深圳学院 Tsinghua-Berkeley Shenzhen Institute TBSI



雷达信号处理国家级重点实验室 National Key Laboratory of Radar Signal Processing



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